



Airborne remote sensing instrumentation for the National Ecological Observatory Network

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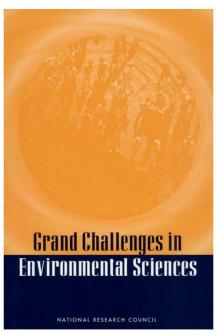
NEON's mission is to enable understanding and forecasting of climate change, land use change, and invasive species on continental-scale ecology -- by providing infrastructure and consistent methodologies to support research and education in these areas.

- **Information infrastructure:** Consistent, continental, long-term, multi-scaled data sets that serve as a context for research and education. All data free and openly available.
- **Physical Infrastructure:** A research platform for investigator-initiated experiments, new sensors and observations at NEON sites.

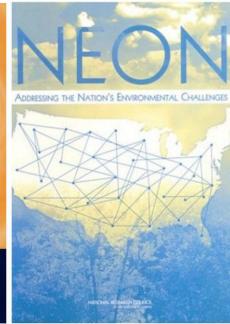


Grand Challenges in Environmental Sciences

- 1. Biodiversity
- 2. Biogeochemical cycles
- 3. Climate change
- 4. Ecohydrology
- 5. Infectious disease
- 6. Land use
- 7. Invasive Species



National Research Council Press 2001 Washington DC

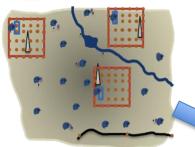


National Research Council Press 2003 Washington DC

NEON groups





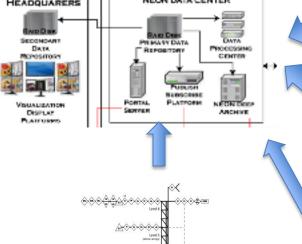


Biological sampling (FSU)



Aquatics and Stream Experiment (STREON)





Flux towers (FIU)



Airborne remote sensing (AOP)



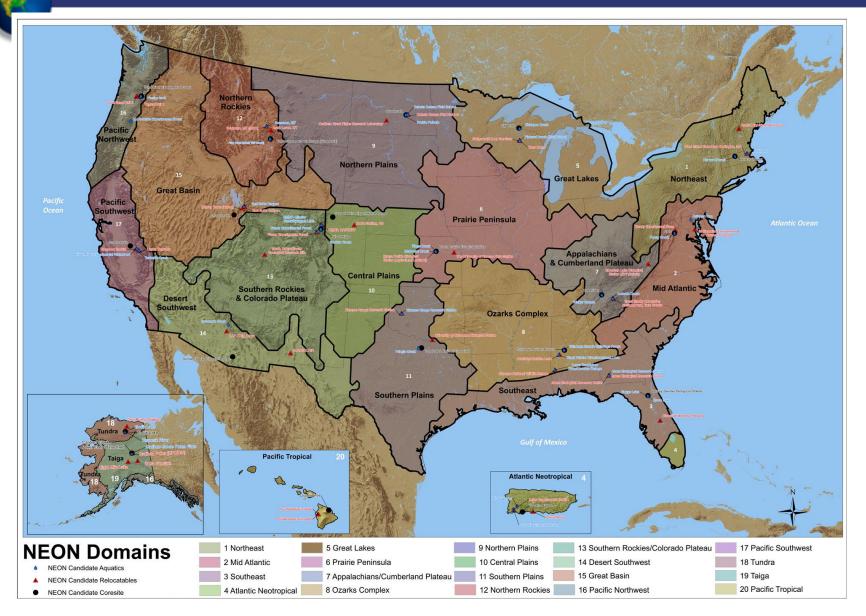
Satellite remote sensing (LUAP)



Civil science

NEON's 60 sites in 20 Domains

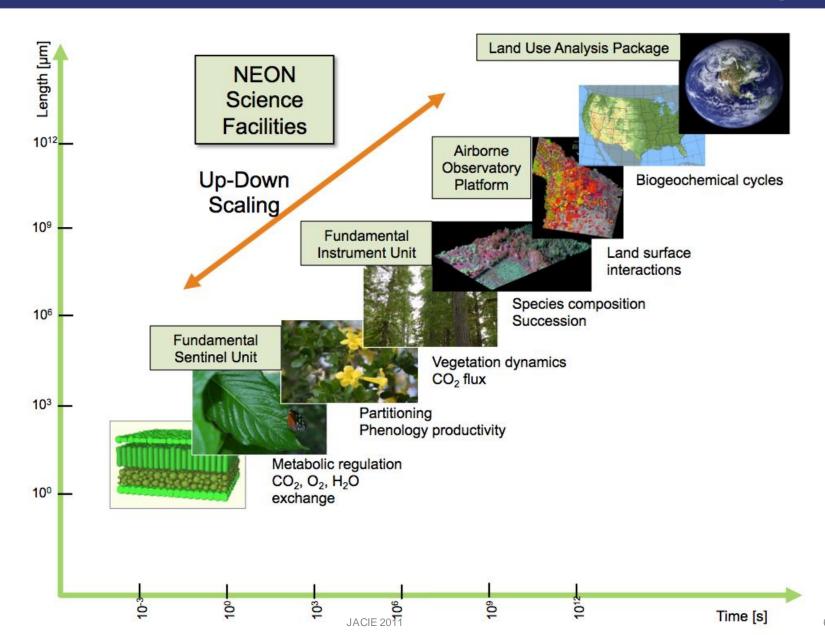




NEON scaling Strategy











- NEON mission
- Airborne package
 - Imaging spectrometer
 - Operations
 - Calibration plan
- Pathfinder Flight 2010 with AVIRIS
 - Airborne data
 - Ground data

Role of Airborne Remote Sensing





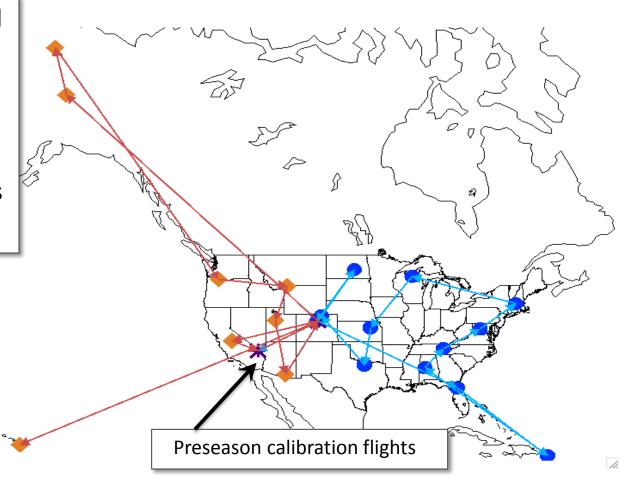
- AOP will observe invasive species, land use drivers and ecosystem responses surrounding the NEON Core and Re-locatable sites
 - land cover
 - vegetation structure
 - Invasive plant species
 - biochemical and biophysical properties
 - ecosystem functioning
- Bridge scales from organism and stand scales to the scale of satellite based remote sensing (e.g. meter-scale)
- Observe targets of opportunity (e.g. PI-science, wildfires)

Airborne Operations





- 2 aircraft with identical payloads to cover sites
- 7-months, 1,100 flight hrs flight season
- 3rd Payload for backup
 & new science, targets
 of opportunity

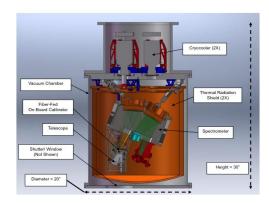


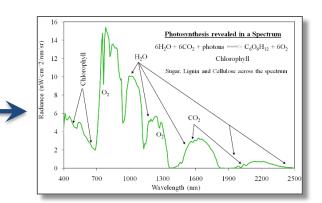
Airborne Observation Platform





Imaging SpectrometerJPL



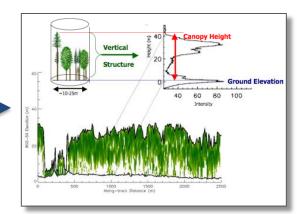


Waveform lidar

Optech ALTM Gemini system

Applanix GPS/IMU





High-resolution digital camera

Applanix digital airborne camera





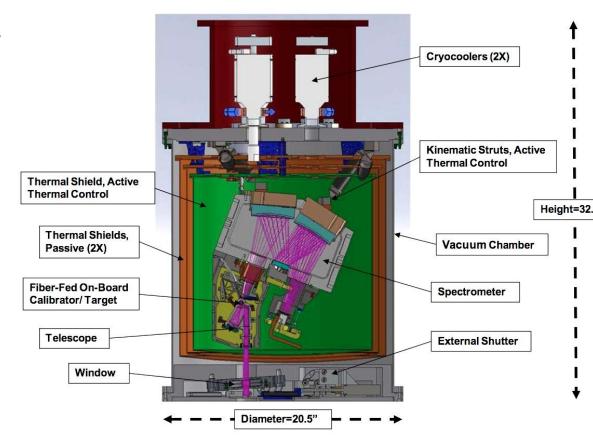




Neon Imaging Spectrometer Design Verification Unit (DVU)



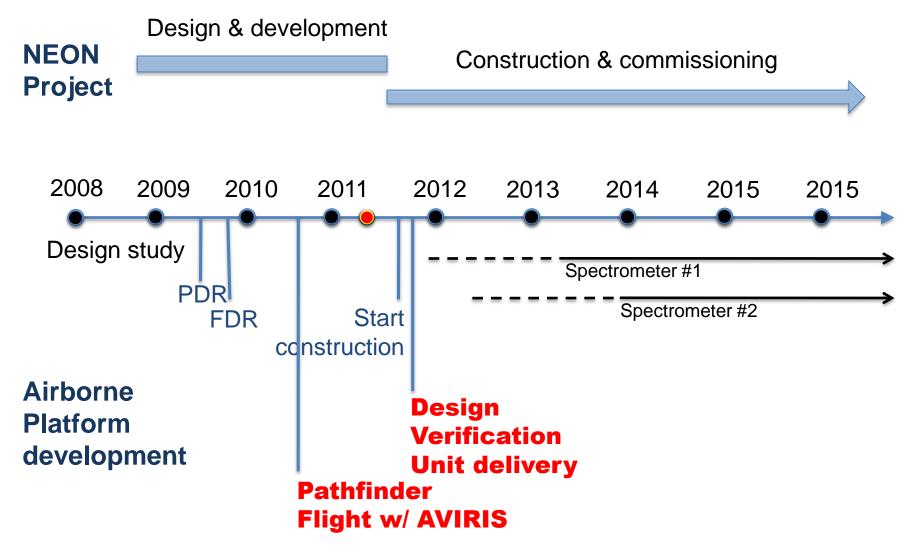
- Pushbroom imaging spectrometer
- Spectral range: 380 2510 nm
- Spectral sampling: 5 ± 0.5 nm
- FOV: 34 ± 1 degrees
- IFOV: 1 ± 0.1 mrad
- Radiometric sampling: 14 bit
- Crosstrack swath: 1 km @ 1 km AGL
- Spectral-cross-track uniformity: >95% uniformity
- Spectral-IFOV: > 95% uniformity
- Configuration: Two-mirror off-axis telescope, single Offner spectrometer with multi-blaze grating, mechanical coolers



Status of Airborne Observation Platform







DVU Development status

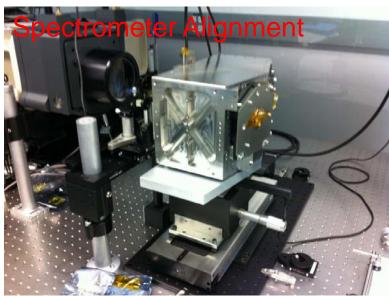




- 2008-Dec Completed JPL conceptual design study & early risk reduction tasks
- 2009-Feb Subsystem design reviews
- 2009-Oct 2012-Apr
 - Spectrometer design verification unit (DVU)
 - Prototype algorithms
 - Flight campaigns (inc. 2010 pathfinder)





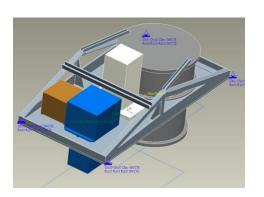




Calibration timeline for airborne platform



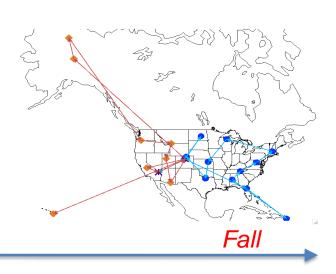








Spring



Pre flight season laboratory characterization at NEON HQ in Boulder, CO Pre flight season operational test.
Coincident measurements of:

- -3 airborne platforms
- -Satellite sensors
- -Ground-based reflectance and atmosphere

Flight season characterization:

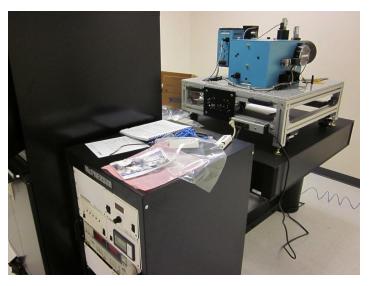
- -On-board calibrator
- -Known test sites
- -Solar radiation based calibration

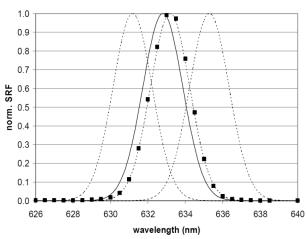
Calibration Facility – Spectral





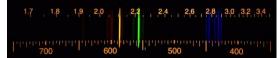
Monochromator





Rare gas spectra

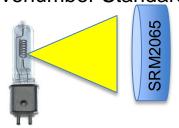




Laser sphere



SRM 2065 - Ultraviolet-Visible-Near-Infrared Transmission Wavelength/Vacuum Wavenumber Standard

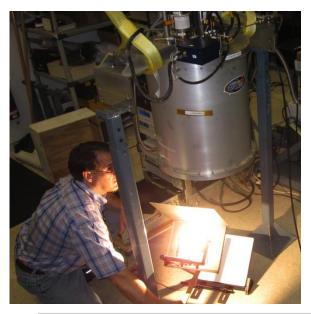


Calibration Facility – Radiometric

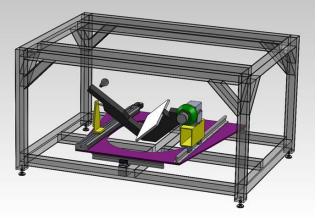




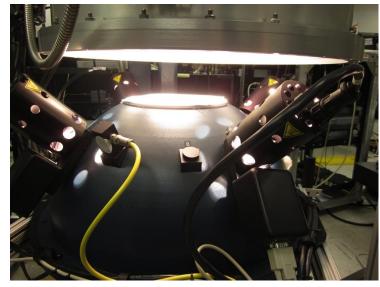
NIST irradiance standard

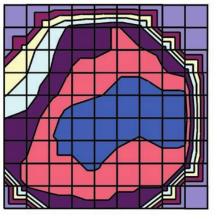


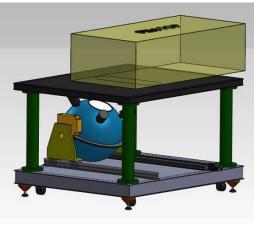




Integrating-sphere source











NEON Domain 3 core site: Ordway-Swisher Biological Station, Florida

Prototype to incorporate multiple NEON datastreams to

- Develop scaling strategies
- Ground-truth airborne measurements

Field sampling measurements

- Tree diversity
- Vegetation structure
- Leaf Area Index (LAI)

Airborne measurements

Imaging spectroscopy





Pathfinder 2010 photos

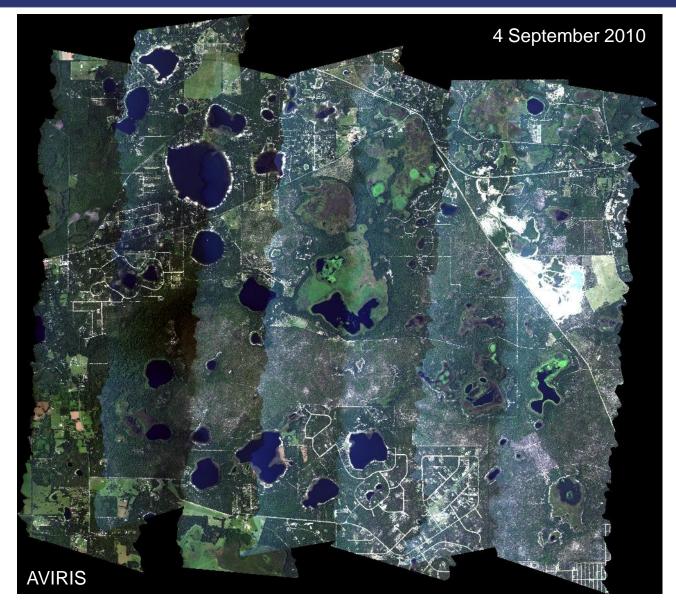




Pathfinder 2010 – Imaging Spectrometer



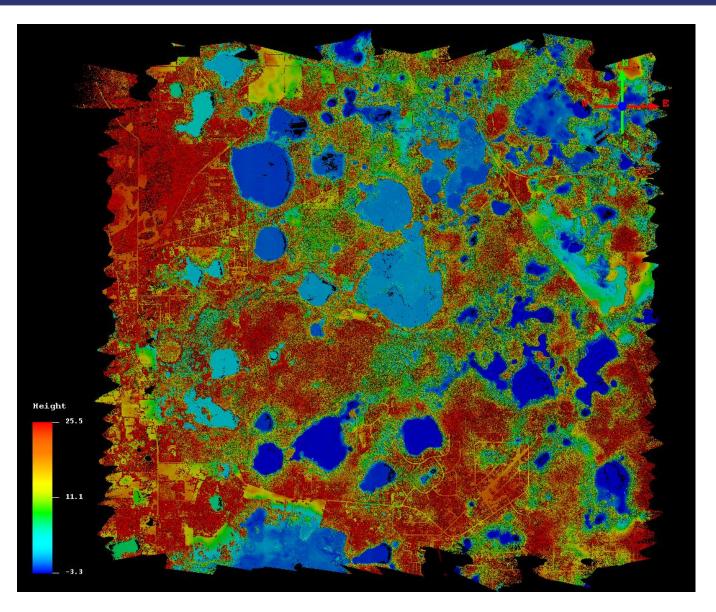




Pathfinder 2010 – Waveform lidar

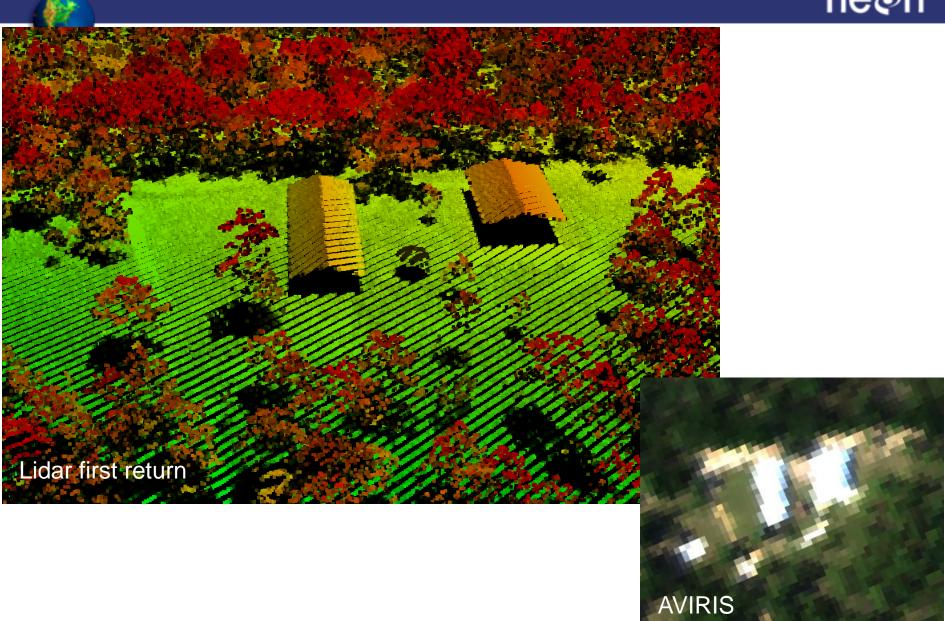






Lidar

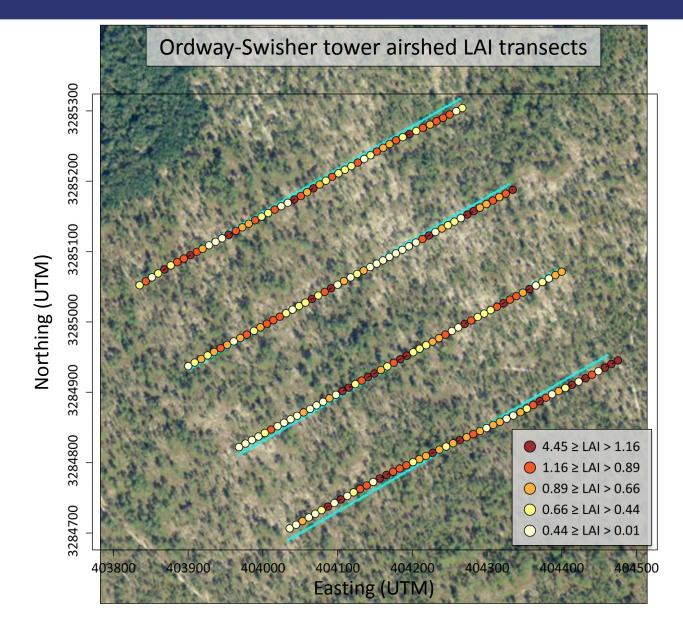




Leaf Area Index data

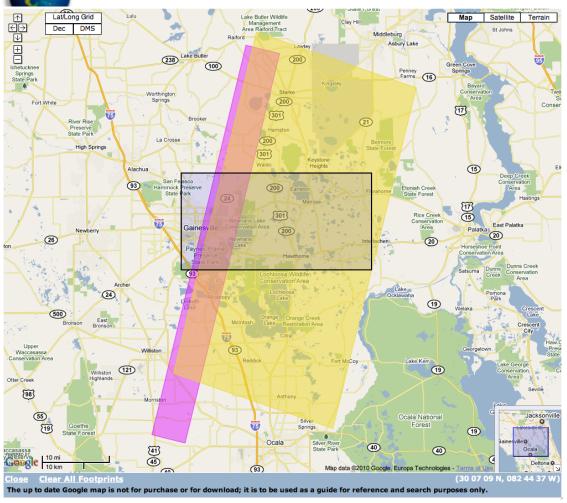




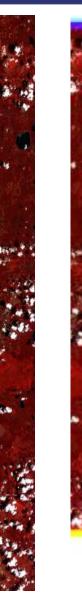


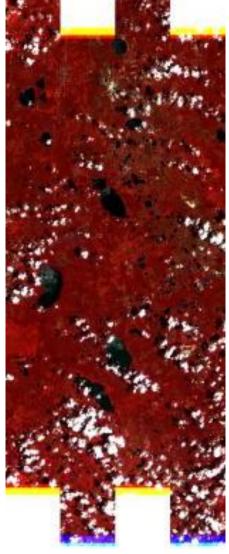
EO-1 on September 3, 2010





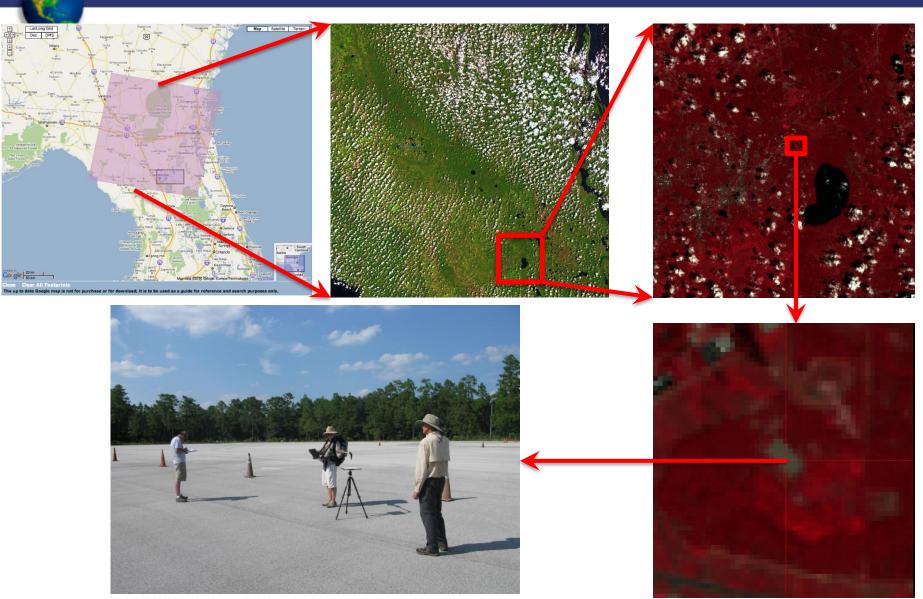
Hyperion = pink footprint Advanced Land Imager = yellow footprint Campaign area = Black outline





Radiometric Cal site - Landsat 5TM



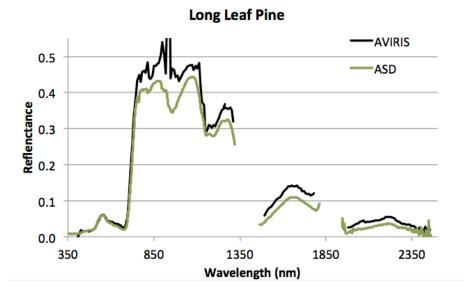


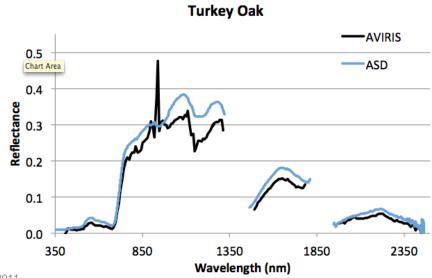
AVIRIS and ground spectra









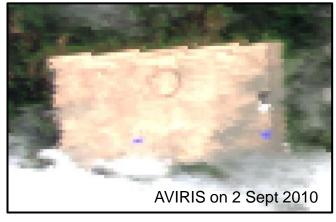


Measurements for vicarious calibration

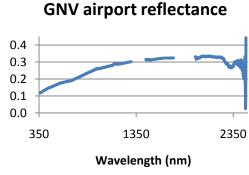




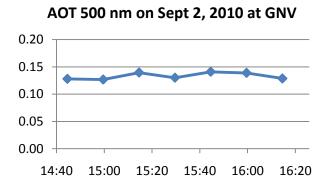
Gainsville Airport Test Site



Ground reflectance



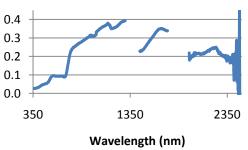
Atmospheric characterization



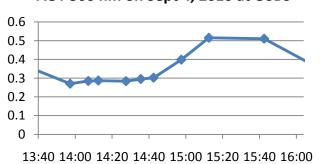
Ordway Test Site



OSBS veg cal target reflectance



AOT 500 nm on Sept 4, 2010 at OSBS





- NEON airborne remote sensing will provide a remote sensing capability beyond existing systems in its ability to produce quantitative information about ecosystems drivers and responses with annual coverage
- Airborne instrumentation will provide sub-meter/meter scale measurements to bridge scales from organism and stand scales to the regional scale
- NEON data system will enable free and open exchange of scientific information from the Observatory





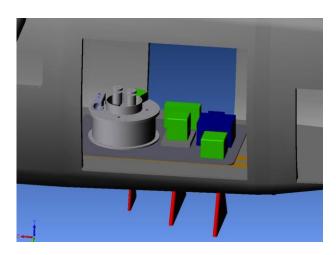
BACKUP / DELETED SLIDES

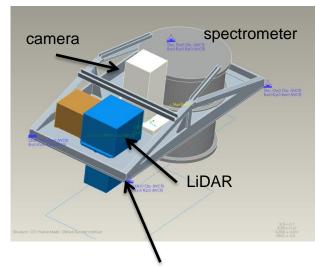
Airborne System Description





- Three airborne remote sensing payloads
 - Imaging spectrometer
 - Waveform lidar
 - High-resolution camera
 - GPS-Inertial measurement unit
- Leased Twin Otter aircraft
- Instrument maintenance and calibration facility
- Science and flight operations





Payload Integration Mount (PIM)